

A Two-Domain Spectral Method for Solving the Constraint Equations of Binary Black Holes with Alternative Initial Data Schemes

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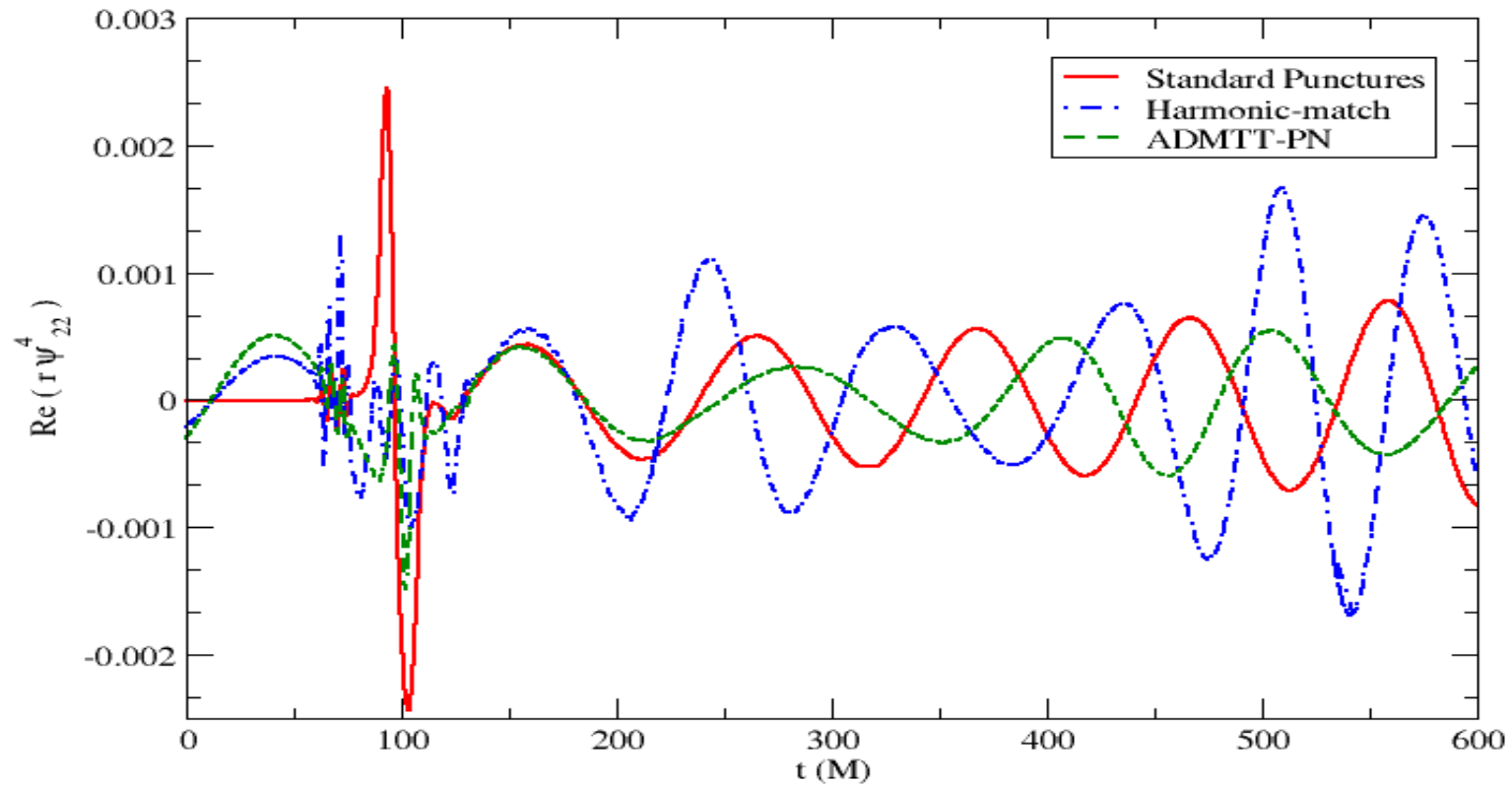
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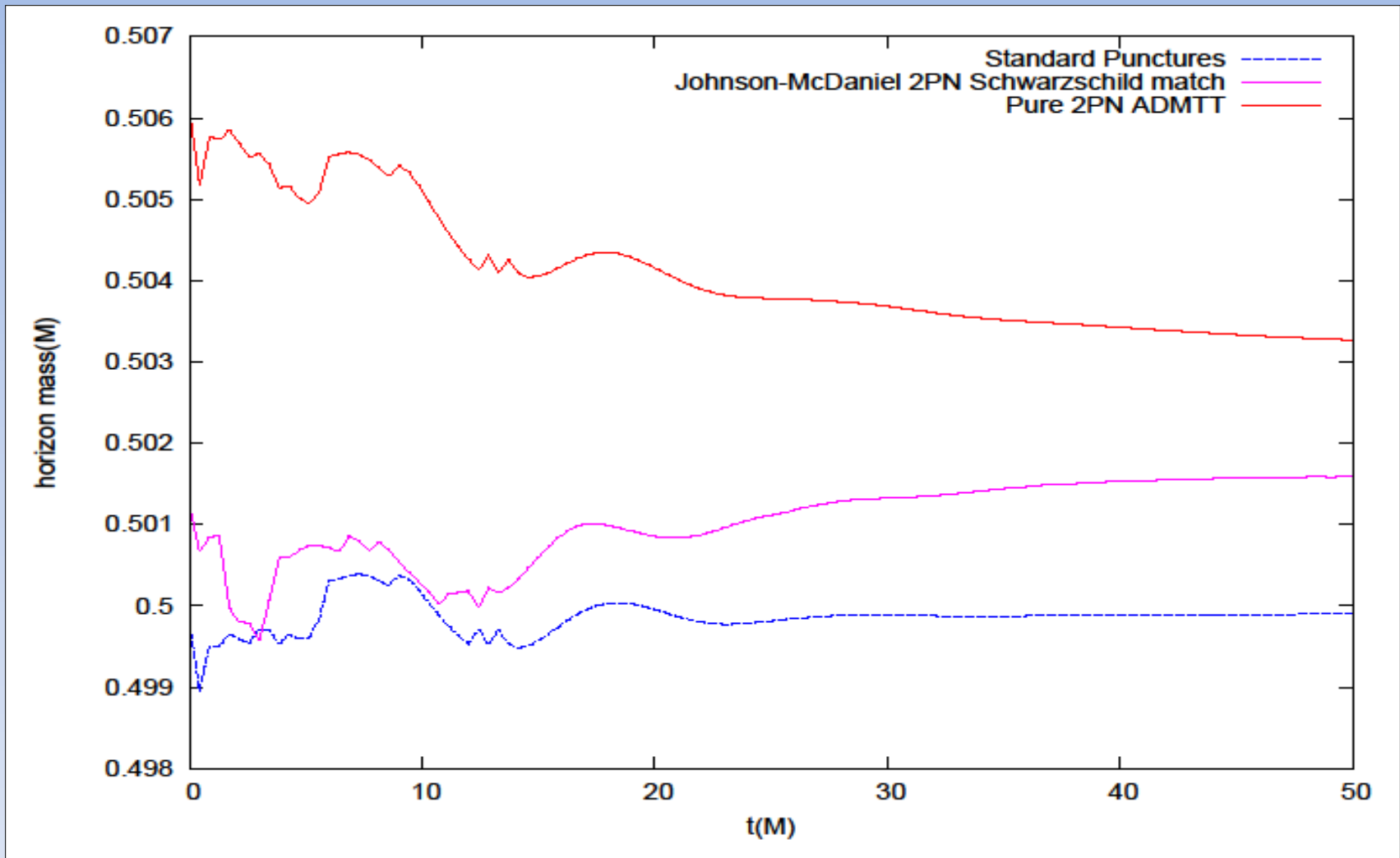
Outline

- **Motivation**
- **Two-Domain Grid**
- **Pseudo-spectral Method**
- **Constraint Solving**

Motivation



Motivation



Motivation

- **Constraint solving may further validate schemes**
 - **Use a conformal decomposition and CTTD**

$$g_{ij} = \Psi^4 \bar{g}_{ij}$$

$$K^{ij} = \Psi^{-10} (\bar{A}^{ij} + \bar{L}W^{ij})$$

- **Also use the Punctures technique to control divergent behavior**

$$\Psi = \psi + u$$

Motivation

- **Constraint Equations become a set of 4 elliptic equations**

$$0 = \bar{\nabla}^2 \Psi - \frac{1}{8} \Psi \bar{R} + \frac{1}{8} \Psi^{-7} (\bar{A}^{ij} + \bar{L}W^{ij})(\bar{A}^{kl} + \bar{L}W^{kl}) \bar{g}_{ik} \bar{g}_{jl}$$
$$0 = \bar{\Delta}_L W^i + \bar{\nabla}_j \bar{A}^{ij}$$

$$\bar{L}W^{ij} = \bar{\nabla}^i W^j + \bar{\nabla}^j W^i - \frac{2}{3} \bar{g}^{ij} \bar{\nabla}_k W^k, \quad \bar{\Delta}_L W^i = \bar{\nabla}_j \bar{L}W^{ij}$$

Two-Domain Spectral Grid

- **General method for computing initial data for binaries**
 - **We choose: Two-Domains for Excised Binary Black Holes**

- **Developed by Marcus Ansorg as a way to**
 - **Compactify spatial infinity to a finite grid**
 - **Resolve data at infinity**
 - **Deal with puncture singularities (If using Puncture data)**

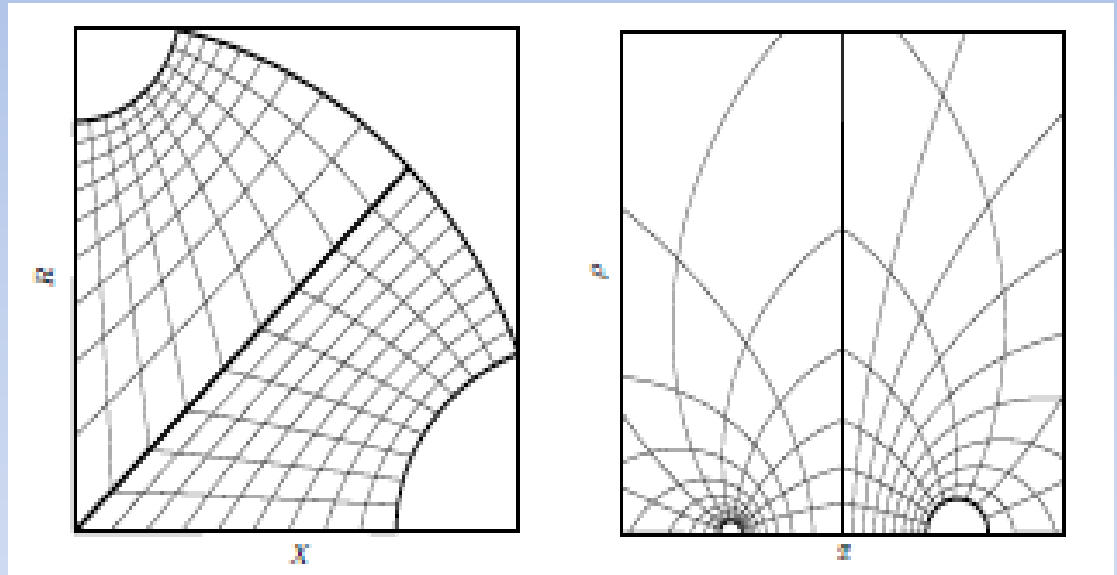
Two-Domain Spectral Grid

- Involves several coordinate transformations

$$(x, y, z) \rightarrow (x, \rho, \varphi)$$

$$(x, \rho, \varphi) \rightarrow (X, R, \varphi)$$

$$(X, R, \varphi) \rightarrow (A, B, \varphi)$$



- Grid points are the collocation points of the pseudo-spectral method

Pseudo-spectral Method

- **An alternative to finite-differencing to accurately compute spatial derivatives**
 - Global vs. Local calculation
- **A function can be expressed as a set of basis functions**

$$L\phi = \Phi(\mathbf{x})$$

$$\text{Let : } \phi(\mathbf{x}) = \sum_{m=0}^N C_m f_m(\mathbf{x})$$

Pseudo-spectral Method

- E.g. Fourier Series

$$\text{If : } \nabla_{\mathbf{x}} \phi = \Phi(\mathbf{x}) \quad \text{Let : } \phi(\mathbf{x}) = \sum_{m=0}^N C_m e^{imx}$$

$$\phi_n = \phi(\mathbf{x}_n)$$

$$\phi(\mathbf{x}_n) = \sum_{m=0}^N C_m e^{imx_n}, \quad \mathbf{x}_n = \frac{2\pi n}{N}$$

$$\begin{pmatrix} \phi_0 \\ \phi_1 \\ \dots \\ \phi_{n-1} \end{pmatrix} = \left(M \right) \begin{pmatrix} C_0 \\ C_1 \\ \dots \\ C_{n-1} \end{pmatrix}$$

Pseudo-spectral Method

- **Function values and coefficients stored after first computations**
- **At collocation points we have a 1:1 relation between function values and coefficients through FFTs**
- **Any derivative operation can be handled later with the coefficients (Spectral) or the function values (Pseudo-spectral)**

$$\nabla_x \phi(x_n) = \sum_{m=0}^N (im) \cdot C_m e^{imx_n} = \sum_{m=0}^N (im) \cdot \phi_n$$

Pseudo-spectral Method

- **More efficient as the resolution increases compared to a finite- difference method**
- **Has the potential for “exponential convergence”**

$$\varepsilon \approx O \left[\left(\frac{1}{N} \right)^N \right]$$

Pseudo-spectral Method

- Choice of basis functions depends on problem properties
 - Fourier, Chebyshev, Hermite, Laguerre
- Our domain is suited for Fourier and Chebyshev basis functions
- Our Boundary Conditions determine the collocation points
 - Conformal factor $\rightarrow 0$ as $r \rightarrow \text{inf}$
 - We use the zeroes of the Chebyshev functions as the collocation points

$$A_l = \frac{1}{2} \left[1 - \text{Cos} \left(\frac{\pi l}{n_A - 1} \right) \right] \quad B_l = \frac{1}{2} \left[1 - \text{Cos} \left(\frac{\pi l}{n_B - 1} \right) \right]$$

Constraint Solving

- Solving multi-dimensional non-linear elliptic equations can be time-consuming and inefficient if done improperly
- Standard approach is to use the Newton-Raphson technique

$$F_i(x_1, x_2, \dots, x_N) = 0$$

$$F_i(\mathbf{x} + \delta\mathbf{x}) = F_i(\mathbf{x}) + \sum_{j=1}^N \frac{\partial F_i}{\partial x_j} \delta x_j + O(\delta\mathbf{x}^2)$$

$$\mathbf{F}(\mathbf{x} + \delta\mathbf{x}) = \mathbf{F}(\mathbf{x}) + \mathbf{J} \cdot \delta\mathbf{x} + O(\delta\mathbf{x}^2)$$

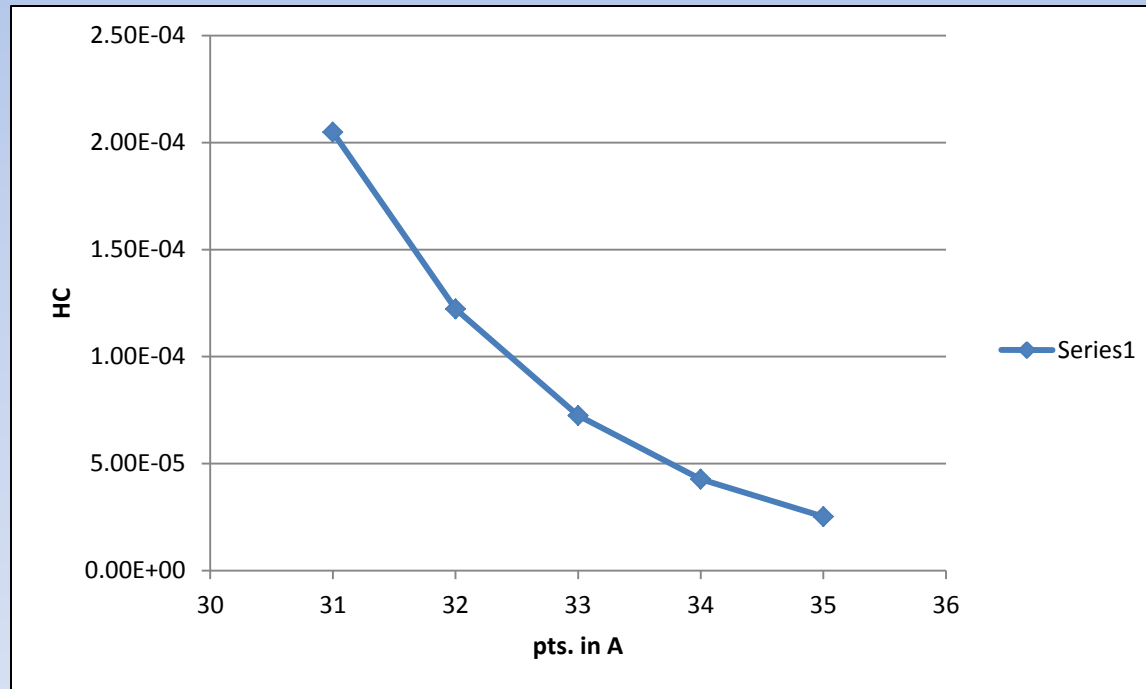
$$\mathbf{J} \cdot \delta\mathbf{x} = -\mathbf{F}$$

Constraint Solving

- **Each iteration moves the functions closer to zero until convergence**
- **Many choices of iteration method (We choose GMRES)**
- **The speed/efficiency of the N-R routine is highly dependent on the initial guess for each root**
- **We can reduce the matrix solving time by preconditioning J**
 - **Same solution with more favorable matrix properties**
 - **Can use the finite difference J as a preconditioner (More sparse)**

Results

- Convergence for ADMTT near Initial data



More Results?

- **Currently working on solving ADMTT full Initial Data**
 - **Debugging** underway at the moment
- **We will also solve the Johnson-McDaniel 2PN Schwarzschild match data**
- **If our level of accuracy is comparable to punctures data, we will incorporate the solving into our evolutions with BAM**
 - **Interpolation back onto a finite Cartesian grid of equally-spaced grid points**

Bibliography

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